

Here $q, q_1, q_2 \in \mathbb{H}$, $a, b, c, d, x, y, z, w \in \mathbb{R}$, $\vec{v} \in \mathbb{R}^3$ (identified with the last three components of a quaternion), $z_1, z_2 \in \mathbb{C}$.

- (1) First we present three formulas which can be used to define quaternionic multiplication (depending on whether we think of \mathbb{H} as \mathbb{R}^4 , \mathbb{C}^2 , or $\mathbb{R} \times \mathbb{R}^3$).

- $$(a + b\mathbf{i} + c\mathbf{j} + d\mathbf{k})(x + y\mathbf{i} + z\mathbf{j} + w\mathbf{k})$$

$$= (ax - by - cz - dw) + (bx + ay + dz - cw)\mathbf{i} + (cx + az + bw - dy)\mathbf{j} + (aw + dx + cy - bz)\mathbf{k}$$

- $$(z_1, z_2)(w_1, w_2) = (z_1w_1 - z_2\bar{w}_2, z_1w_2 + z_2\bar{w}_1)$$

- $$(a, \vec{v})(b, \vec{w}) = (ab - \vec{v} \cdot \vec{w}, a\vec{w} + b\vec{v} + \vec{v} \times \vec{w})$$

- (2) Here are some formulas related to the conjugate.

- $$\overline{q_1 + q_2} = \bar{q}_1 + \bar{q}_2$$

- $$\bar{\bar{a}} = a$$

- $$\overline{\vec{v}} = -\vec{v}$$

- $$\overline{a\bar{q}} = aq$$

- When $q \in \mathbb{S}^3$ (identified with quaternions whose length is 1) we have

$$\bar{q} = q^{-1}$$

- $$\bar{q}q = q\bar{q} = \|q\|^2$$

- $$\overline{q_1q_2} = \bar{q}_2\bar{q}_1 \quad (\text{notice the reverse!})$$

- (3) A few more general facts/ formulas

- When $q \in \mathbb{S}^2$ (identified with pure quaternions whose length is 1) we have

$$q^2 = -1$$

- $$(q_1q_2)^{-1} = q_2^{-1}q_1^{-1}$$